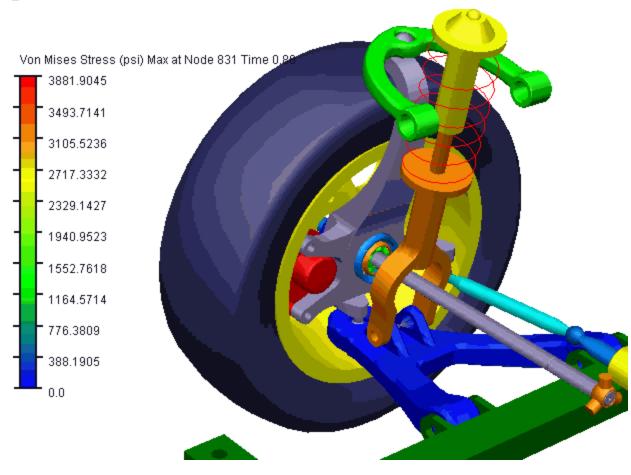
# **Columns & Struts**

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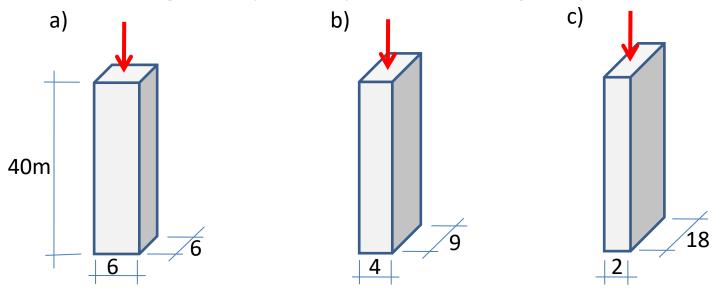
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Load carried by a short column

 $P = \sigma A$  where  $\sigma$  - Stress intensity

A - Cross - sectional Area

- If  $\sigma$  is the ultimate crush stress for the column, then P shall be the crushing load for the column.
- Columns do not generally fail only due to crushing, they buckle too.



- Keeping cross-section area the same but varying the side.
- Column c) likely to fail by buckling.

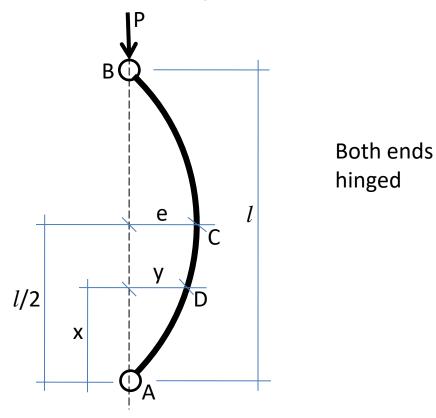
- Also the load carrying capacity reduces with increase in height.
- .:. shall depend on <u>slenderness</u> of the column.

Slendernes s Ratio =  $\frac{\text{Height of Column}}{\text{Least Side of Column}}$ Also =  $\frac{\text{Height of Column}}{\text{Least radius of Gyration (r)}} = \frac{l}{r_{x,y}}$ Where  $r_{x,y} = \sqrt{\frac{I_{x,y}}{A}}$ ,  $I_{x,y}$  - Corresponding Moment of Inertia

- A Cross sectional Area Apart from the slenderness, the load carrying capacity depends upon its end condition too to fix the column.
- At a certain critical load a column shall start bending after which failure of column is certain.

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Consider a straight column AB of length *l* that buckles under load P such that the mid-point C has a max eccentricity e.



Section C is subjected to max moment

 $M = P \ge e$ 

The max and min stress intensifies due to the combination effect of direct & bending stresses  $\sigma_d$  and  $\sigma_b$  are

$$\sigma_{\max} = \sigma_d + \sigma_b = \frac{P}{A} + \frac{Pe}{Z}$$
$$\sigma_{\min} = \sigma_d - \sigma_b = \frac{P}{A} - \frac{Pe}{Z}$$

Column shall fail when either  $\sigma_{max}$  reaches the ultimate crush stress OR when  $\sigma_{min}$  reaches the ultimate tensile strength of the column material.

- Column that fails primarily due to direct stress is called a short column.
- Column that fails primarily due to bending stress is called a long column.
- Short columns are those whose length is less than 8 times the diameter (or the smallest side).

Z – section modulus

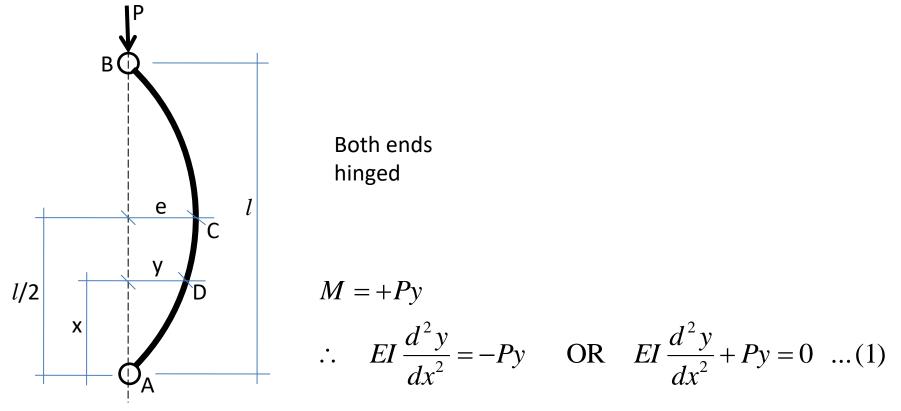
# **Euler's formulation**

His analysis is based on following assumptions:

- a) The columns are initially straight.
- b) The columns are made of homogeneous material.
- c) The columns carry perfectly axial loads.
- d) The columns have uniform cross-sectional areas throughout.
- e) The columns are long compared to lateral dimensions.
- f) Self weight of the columns is neglected.
- g) The columns fail only due to buckling.
- h) Shortening of columns due to direct loading is neglected.
- i) Stresses do not exceed the limit stress of the material.

## 1) Both Ends Hinged

Consider a long column of effective length l, hinged at both ends crippling under an axial load, called Euler's Crippling load  $P_E$ . Assume a small internal force buckles the column. Let the eccentricity at any D at a height x from A be y. The moment at the point is



If we set

$$\frac{P}{EI} = k^2 \quad \dots (2)$$

then the differential equation of deflection becomes

$$\frac{d^2 y}{dx^2} + k^2 y = 0 \quad ... (3)$$

- When solving the above equation, we need merely find a function which when differentiated twice and added to itself (times a constant) is equal to zero.
- Evidently either sin kx or cos kx possesses this property. In fact, a combination of these terms in the form,

 $y(x) = C \sin kx + D \cos kx \quad \dots \quad (4)$ 

 May be taken as solution of eqn (3). This may be readily checked by substituting y(x) into eqn (3). To determine C and D: at A, y = 0 when x = 0. substituting these values in eqn (4), we obtain,

$$0 = 0 + D \qquad \text{or} \qquad D = 0$$

At **B**, y = 0 when x = l. Substituting these values in eqn (4) with **D** = 0, we obtain,

 $0 = C \sin kl$ 

Evidently either C = 0 or sin kl = 0. But if C = 0 then y is everywhere zero and we have only the trivial case of a straight bar which is configured prior to the occurrence of buckling. Therefore we take

$$\sin kl = 0 \quad \dots \quad (5)$$

For this to be true, we have

$$kl = n\pi$$
 ( $n = 1, 2, 3...$ ) ...(6)

Substituting 
$$k^2 = \frac{P}{EI}$$
 in eqn (6), we find  
 $\sqrt{\frac{P}{EI}l} = n\pi$  or  $P = \frac{n^2 \pi^2 EI}{l^2}$  ...(7)

The smallest value of this load evidently occurs when **n=1**. Then we have the so-called first mode of buckling where the **critical load** is given by

$$P_{cr} = \frac{\pi^2 EI}{l^2} \dots (8)$$

This is *Euler's buckling load for pin-ended column*. The deflection shape corresponding to this load is

$$y(x) = C \sin\left(\sqrt{\frac{P}{EI}}x\right) \dots (9)$$

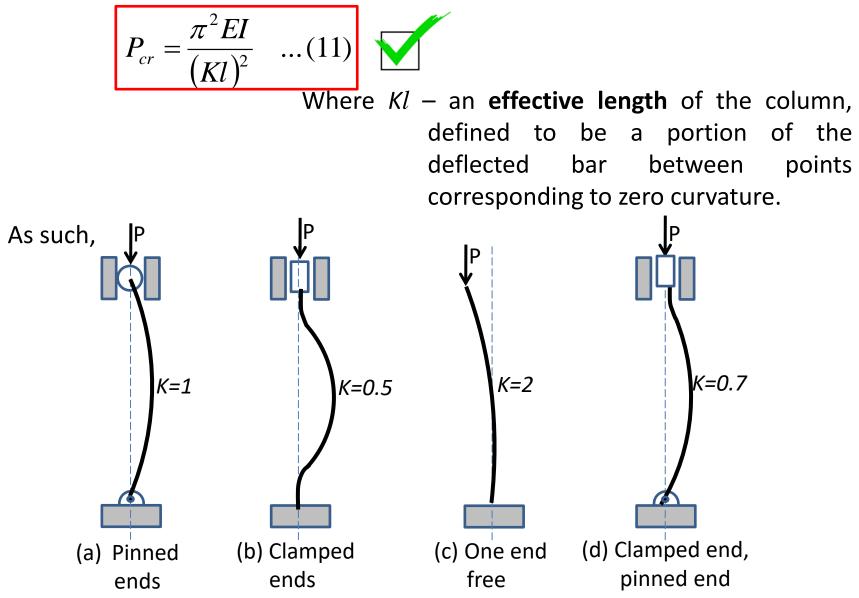
Substituting eqn (8) into (9), we obtain

$$y(x) = C\sin\frac{\pi x}{l} \dots (10)$$

Note that the deflected shape is a Sine function

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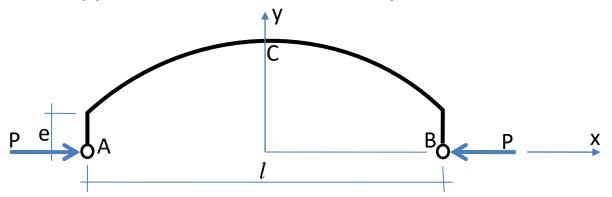
Eqn (8) may be modified to the form



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#### **Eccentrically loaded Columns**

Assume an initially straight, pin-ended column subjected to an axial compressive force applied with know eccentricity e.



The differential equation of a bar in its deflected configuration if

$$EI\frac{d^2y}{dx^2} = -Pe \quad \dots (11)$$

Which has a standard solution

$$y = C_1 \sin\left(\sqrt{\frac{P}{EI}}x\right) + C_2 \cos\left(\sqrt{\frac{P}{EI}}x\right) \dots (12)$$

Since y = e at each ends, x=-l/2 and x=l/2, the value of the two constants of integration are readily found to be

$$C_1 = 0 \qquad C_2 = \frac{e}{\cos\left(\sqrt{\frac{P}{EI}} \frac{l}{2}\right)} \qquad \dots (13)$$

Therefore , the deflection curve of the bent bar is

$$y = \frac{e}{\cos\left(\sqrt{\frac{P}{EI}} \frac{l}{2}\right)} \cos\left(\sqrt{\frac{P}{EI}} x\right) \qquad \dots \quad (14)$$

The max value of deflection occurs at x = 0

$$y_{\text{max}} = e \sec\left(\sqrt{\frac{P}{EI}} \frac{l}{2}\right) \qquad \dots (15)$$

Introducing the value of the critical load  $P_{cr}$  as given by eqn (8)

$$y_{\text{max}} = e \sec\left(\frac{\pi}{2}\sqrt{\frac{P}{P_{cr}}}\right) \qquad \dots (16)$$

The max compressive stress occurs on the concave side of the bar at C and its given by

$$\sigma_{\max} = \frac{P}{A} + \frac{M_{\max} y_c}{I} = \frac{P}{A} + \frac{Pe y_c}{I} \sec\left(\frac{\pi}{2}\sqrt{\frac{P}{P_{cr}}}\right) \dots (17)$$

 $y_c$  – distance from neutral axis to outer fibre of bar.

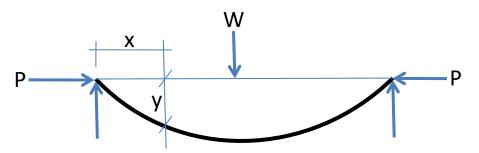
If we introduce the radius of gyration *r* of the cross-section, this becomes:

$$\sigma_{\max} = \frac{P}{A} + \frac{M_{\max} y_c}{I} = \left[\frac{P}{A} \left[1 + \frac{e y_c}{r^2} \sec\left(\frac{l}{2r} \sqrt{\frac{P}{AE}}\right)\right]\right] \dots (18)$$

## Struts with transverse loading also

## a) Point load at mid span

Let the strut AB of length *l*, hinged at ends, carry transverse load W at mid span and a thrust at ends. Let this strut so deflect that at x from support A the deflection is y.



B.M at distance x from A is  $+\left(Py + \frac{W}{2}x\right)$ 

$$EI\frac{d^2y}{dx^2} = -\left(Py + \frac{W}{2}x\right)$$

or  $\frac{d^2 y}{dx^2} + \frac{P}{EI} y + \frac{W}{2EI} x = 0$ 

Solution to above differential equation is:

$$y = C_1 \cos\left(\sqrt{\frac{P}{EI}}x\right) + C_2 \sin\left(\sqrt{\frac{P}{EI}}x\right) - \frac{Wx}{2P}$$

To determine constants  $C_1$  and  $C_2$  apply end condition at A where y = 0 when x = 0, therefore  $C_1 = 0$ 

Thus 
$$y = C_2 \sin\left(\sqrt{\frac{P}{EI}}x\right) - \frac{Wx}{2P}$$
  
 $\therefore \qquad \frac{dy}{dx} = C_2 \sqrt{\frac{P}{EI}} \cos\left(\sqrt{\frac{P}{EI}}x\right) - \frac{W}{2}$ 

At mid span where

$$x = \frac{l}{2}; \quad \frac{dy}{dx}$$
 is zero

 $\overline{P}$ 

$$0 = C_2 \sqrt{\frac{P}{EI}} \cos \frac{l}{2} \sqrt{\frac{P}{EI}} - \frac{W}{2P}$$
$$C_2 = \frac{W}{2P} \sqrt{\frac{EI}{P}} \sec \frac{l}{2} \sqrt{\frac{P}{EI}}$$
$$y = \frac{W}{2P} \sqrt{\frac{EI}{P}} \sec \frac{l}{2} \sqrt{\frac{P}{EI}} \sin x \sqrt{\frac{P}{EI}} - \frac{Wx}{2P} \dots (a)$$

Thus

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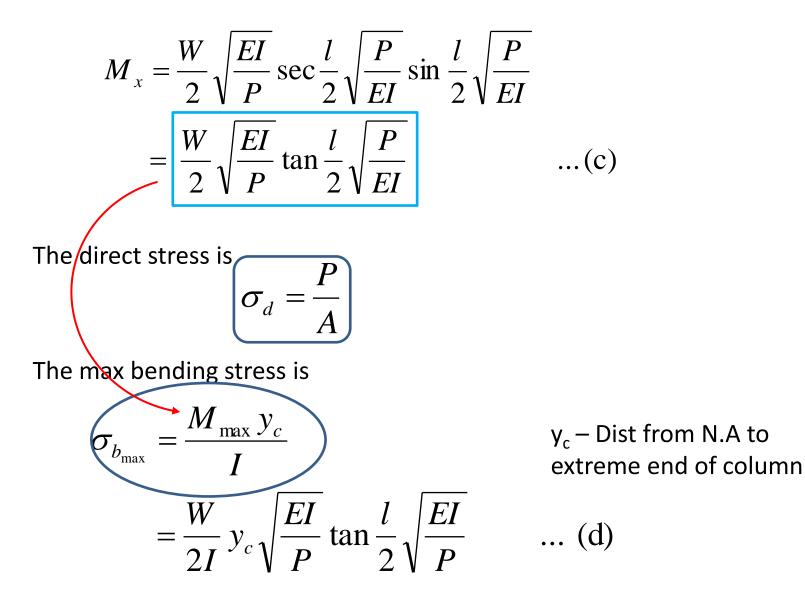
**B.M** at distance x from A is

$$M_{x} = Py + \frac{Wx}{2}$$

$$= \frac{W}{2}\sqrt{\frac{EI}{P}}\sec\frac{l}{2}\sqrt{\frac{P}{EI}}\sin x\sqrt{\frac{P}{EI}} - \frac{Wx}{2P} + \frac{Wx}{2}$$

$$= \frac{W}{2}\sqrt{\frac{EI}{P}}\sec\frac{l}{2}\sqrt{\frac{P}{EI}}\sin x\sqrt{\frac{P}{EI}} \qquad \dots (b)$$

The **B.M**. shall be **max** at mid span where  $\mathbf{x} = l/2$ 



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Therefore, max bending stress is:

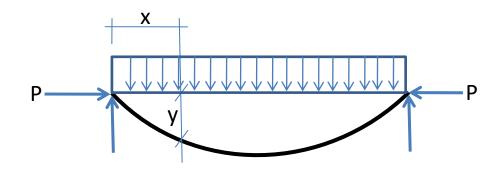
$$\sigma_{\max} = \sigma_d + \sigma_{b_{\max}}$$

$$= \frac{P}{A} + \frac{W}{2I} y_c \sqrt{\frac{EI}{P}} \tan \frac{l}{2} \sqrt{\frac{P}{EI}}$$

$$= \frac{1}{A} \left( P + \frac{Wy_c}{2r^2} \sqrt{\frac{EI}{P}} \tan \frac{l}{2} \sqrt{\frac{P}{EI}} \right) \dots (d)$$

$$(\Theta \qquad I = Ar^2)$$

$$(r - \text{Radius of Gyration})$$



Consider a strut AB of length *l* hinged at both ends carrying a u.d.l of w/unit length. Let the deflection at a distance x from A be y.

**B.M.** at the section is
$$M_{x} = Py + \frac{wl}{2}x - \frac{wx^{2}}{2}$$

Therefore

$$EI\frac{d^2y}{dx^2} = -Py - \frac{wlx}{2} + \frac{wx^2}{2}$$

or

$$\frac{d^2 y}{dx^2} + \frac{P}{EI} y = -\frac{wlx}{2EI} + \frac{wx^2}{2EI}$$

Solution to the differential equation is:

$$y = C_1 \cos \sqrt{\frac{P}{EI}} x + C_2 \sin \sqrt{\frac{P}{EI}} x - \frac{wlx}{2P} - \frac{wEI}{P^2} + \frac{wx^2}{2P}$$

To determine C<sub>1</sub> apply end condition at A where y = 0 when x = 0. Therefore  $0 = C_1 - \frac{wEI}{P^2}$  or  $C_1 = \frac{wEI}{P^2}$ 

Thus

$$y = \frac{wEI}{P^2} \cos \sqrt{\frac{P}{EI}} x + C_2 \sin \sqrt{\frac{P}{EI}} x - \frac{wlx}{2P} - \frac{wEI}{P^2} + \frac{wx^2}{2P}$$

Therefore

$$\frac{dy}{dx} = -\frac{wEI}{P^2} \sqrt{\frac{P}{EI}} \sin \sqrt{\frac{P}{EI}} x + C_2 \sqrt{\frac{P}{EI}} \cos \sqrt{\frac{P}{EI}} x - \frac{wl}{2P} + \frac{wx}{P}$$

At mid span where x = l/2; dy/dx = 0

$$0 = -\frac{wEI}{P^2}\sqrt{\frac{P}{EI}}\sin\frac{l}{2}\sqrt{\frac{P}{EI}} + C_2\sqrt{\frac{P}{EI}}\cos\frac{l}{2}\sqrt{\frac{P}{EI}} - \frac{wl}{2P} + \frac{wl}{2P}$$

Therefore,

$$C_2 = \frac{wEI}{P^2} \tan\left(\frac{l}{2}\sqrt{\frac{P}{EI}}\right)$$

Thus

$$y = \frac{wEI}{P^2} \cos \sqrt{\frac{P}{EI}} x + \frac{wEI}{P^2} \tan \left(\frac{l}{2}\sqrt{\frac{P}{EI}}\right) \sin \sqrt{\frac{P}{EI}} x - \frac{wlx}{2P} - \frac{wEI}{P^2} + \frac{wx^2}{2P} \dots (e)$$

Deflection is max at mid span when x = l/2

Therefore,

$$y_{\text{max}} = \frac{wEI}{P^2} \left( \frac{l}{2} \sqrt{\frac{P}{EI}} \right) \cos\left(\frac{l}{2} \sqrt{\frac{P}{EI}}\right) + \frac{wEI}{P^2} \tan\left(\frac{l}{2} \sqrt{\frac{P}{EI}}\right) \sin\left(\frac{l}{2} \sqrt{\frac{P}{EI}}\right)$$
$$-\frac{wl^2}{P^2} - \frac{wEI}{P^2} + \frac{wl^2}{8P}$$
$$= \frac{wEI}{P^2} \cos\left(\frac{l}{2} \sqrt{\frac{P}{EI}}\right) + \frac{wEI}{P^2} \frac{\sin^2\left(\frac{l}{2} \sqrt{\frac{P}{EI}}\right)}{\cos\left(\frac{l}{2} \sqrt{\frac{P}{EI}}\right)} - \frac{wl^2}{8P} - \frac{wEI}{P^2}$$

$$y_{\text{max}} = \frac{wEI}{P^2} \sec\left(\frac{l}{2}\sqrt{\frac{P}{EI}}\right) - \frac{wl^2}{8P} - \frac{wEI}{P^2}$$
$$= \frac{wEI}{P^2} \left[\sec\left(\frac{l}{2}\sqrt{\frac{P}{EI}}\right) - 1\right] - \frac{wl^2}{8P} \qquad \dots \text{ (f)}$$
  
Max B.M is at mid span at x = l/2  
Therefore,
$$M_{\text{max}} = Py_{\text{max}} + \frac{wl}{2}\left(\frac{l}{2}\right) - \frac{w}{2}\left(\frac{l}{2}\right)^2 = Py_{\text{max}} + \frac{wl^2}{8}$$
$$= \frac{wEI}{P} \left[\sec\left(\frac{l}{2}\sqrt{\frac{P}{EI}}\right) - 1\right] - \frac{wl^2}{8} + \frac{wl^2}{8}$$
$$= \frac{wEI}{P} \left[\sec\left(\frac{l}{2}\sqrt{\frac{P}{EI}}\right) - 1\right] - \frac{wl^2}{8} + \frac{wl^2}{8}$$
... (g)

#### Direct stress is

$$\sigma_d = \frac{P}{A}$$

and max bending stress is

$$\sigma_{b_{\text{max}}} = \frac{M_{\text{max}} y_c}{I} = \frac{WE}{P} \left[ \sec\left(\frac{l}{2}\sqrt{\frac{P}{EI}} - 1\right) \right] y_c \qquad \dots \text{(h)}$$

Max compressive stress is

$$\sigma_{\max} = \sigma_d + \sigma_{b_{\max}}$$
$$= \frac{P}{A} + \frac{wE}{P} y_c \left[ \sec\left(\frac{l}{2}\sqrt{\frac{P}{EI}} - 1\right) \right]$$