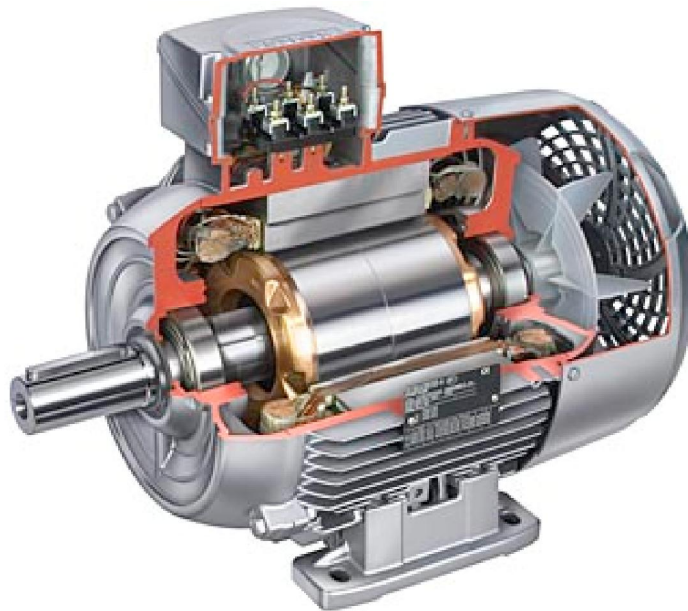


EEE 3352

Electromechanics & Electrical Machines



Lecture 1: Introductory concepts



1. Introductory concepts

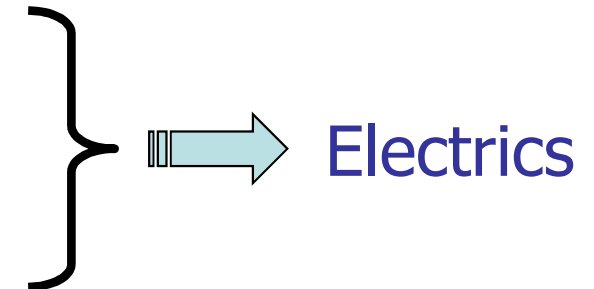
1. Physical quantities, dimensions and units
2. Scalars, vectors, phasors
3. Basic laws:
 - Faraday's
 - Ampere's
 - Newton's 2nd
 - Conservation



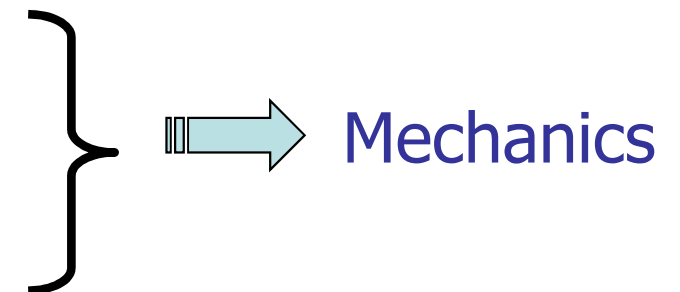
1.1 Physical quantities, dimensions and units

-physical quantities in **electrical engineering** cover what happens in:

-
- conductors & insulators: electric
 - magnetic & non materials: magnetic



-
- mechanical engineering
 - thermodynamics





Some of physical quantities

Mechanical [symbol]

Length	[l or x]
--------	----------------

Force	[F]
-------	---------

Momentum	[Γ]
----------	--------------

Acceleration	[a]
--------------	---------

Torque	[T]
--------	---------

Angular speed	[ω]
---------------	--------------

Mass	[m]
------	---------

Electrical [Symbol]

Voltage	[v , V]
---------	---------------

Resistance	[R]
------------	---------

Capacitance	[C]
-------------	---------

Inductance	[L]
------------	---------

Electric charge	[q , Q]
-----------------	---------------

Current density	[J]
-----------------	---------

Magnetic flux	[ϕ]
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Dimensions and Units

- used to describe physical quantities:

Dimension:

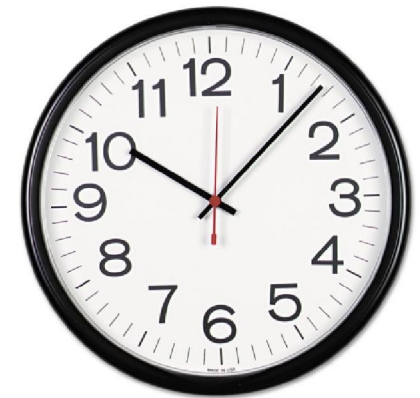
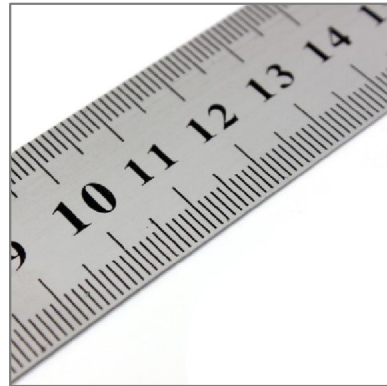
- characteristic of a physical quantity

Unit:


- how the physical quantity is to be measured in terms of standard quantities


- traditionally, 3 reference dimensions in mechanics:

- length
- mass
- time



- 2 more dimensions for
 - electricity and magnetism (e.g. current)
 - thermodynamics (e.g. temperature)

- 
- a number of independent base units
 - need to be chosen
 - carefully defined
 - the actual number being the same as that of the independent dimensions

- 
- SI (International system) - adopted internationally
 - 7 base units
 - 2 supplementary units

SI quantities & units

	Quantity	Unit Name	Unit
Base	Time	second	s
	Length	metre	m
	Mass	kilogram	kg
	Electric current	Ampere	A
	Thermodynamic temperature	Kelvin	K
	Luminous intensity	candela	cd
	Amount of substance	mole	mol
Supp	Plane Angle	radian	rad
	Solid angle	steradian	sr





Units

- definition of units are precise
- in EEE 3352 you need only remember for electric current

see extract from

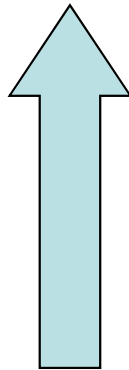
“IET Units and Symbols for Electrical and Electronic Engineering”

- 
- units of all physical quantities can be expressed in terms of the base and supplementary units
 - in practice, it is better to define **derived units** in cases where
 - the quantity is used frequently
 - eg **Hz** derived from **s⁻¹** for frequency
 - the units are lengthy
 - eg **N** for **kgm/s²**
 - a new physical concept is introduced
 - eg **V** for **kgm²s⁻³A⁻¹**

- 
- the numerical values of many quantities may be many **orders** of magnitude away from unity (bigger or smaller)
 - it may be convenient to either use power of **10** or to use **decimal prefixes** with the unit

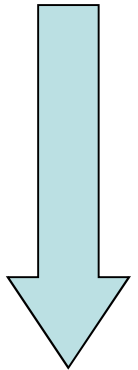
Base 10 and their prefixes

quantity	name	symbol
10^{18}	exa	E
10^{15}	peta	P
10^{12}	tera	T
10^9	giga	G
10^6	mega	M
10^3	kilo	k



quantity	name	symbol
10^2	hecto	h
10^1	deca	da
10^{-1}	deci	d
10^{-2}	centi	c

quantity	name	sym
10^{-3}	milli	m
10^{-6}	micro	μ
10^{-9}	nano	n
10^{-12}	pico	p
10^{-15}	femto	f
10^{-18}	atto	a





Relationships

- **equations** are a compact and effective way of stating relationships between various quantities
- equations may arise in 4 different ways:
 1. a statement of a basic law, tested and accepted e.g. **Faraday's law**, $v = N \frac{d\phi}{dt}$
 2. a definition of a new quantity or concept e.g. electric **current density**, $J = \frac{di}{dA}$
 3. description of material property e.g. **permeability**, $\mu = \frac{B}{H}$
 4. derivation from other equations, using mathematical processes



1.2 Scalars, Vectors and Phasors

Scalar

- has
 - magnitude only
 - is specified by a single numerical value together with its unit
- eg., mass



Vector

- has a **magnitude** and **direction** ;
- needs **2** values to specify it, if it is confined to a **plane**, or
- needs **3** three values, if in **general space**;
- quoted values depend on system: i.e.
 - $x, y (z)$ for Cartesian or;
 - $r, \theta (\omega)$ for polar representation



Phasor

- is a technique for describing any sinusoidally varying quantity;
- in general $y = y_m(\cos \omega t + \phi)$ means the projection of a phasor
 - of magnitude or peak value, y_m ;
 - rotating at angular speed ω onto a fixed reference unit;
 - angle ϕ from reference;
 - at time t will give the instantaneous value of y



1.3 Basic Laws

Maxwell's Equations

general

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particular

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Faraday's Law

$$\nabla \times E = -\frac{\partial B}{\partial t} \rightarrow$$

$$v = N \frac{d\phi}{dt}$$

Ampere's Law

$$\nabla \times H = \frac{\partial D}{\partial t} + J \rightarrow$$

$$Hl = NI$$



Newton's 2nd Law

rectilinear

$$\sum F = m \frac{d^2 x}{dt^2} = ma$$

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$$\sum F = m \frac{d^2 x}{dt^2} = ma = 0$$

rotational

$$\sum T = J \frac{d^2 \theta}{dt^2} = J\alpha$$

$$\sum T = J \frac{d^2 \theta}{dt^2} = J\alpha = 0$$

Law of conservation of energy

Law of conservation of mass



Maxwell's Equations

Gauss's Laws:

- Conservation of electric charge $\nabla \bullet D = \rho$
- Conservation of magnetic flux $\nabla \bullet B = 0$



-End of Lecture 1-